

White Box Testing Techniques



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Organization of this Lecture



⌘ White-box testing:

- ☑ statement coverage
- ☑ path coverage
- ☑ branch testing
- ☑ condition coverage
- ☑ Cyclomatic complexity

⌘ Summary

White-box Testing

⌘ Designing white-box test cases:

☑ requires knowledge about the internal structure of software.

☑ white-box testing is also called structural testing.

White-Box Testing



⌘ There exist several popular white-box testing methodologies:

- ☑ Statement coverage
- ☑ branch coverage
- ☑ path coverage
- ☑ condition coverage
- ☑ mutation testing
- ☑ data flow-based testing

Statement Coverage

⌘ Statement coverage methodology:

- ☑ design test cases so that

- ☒ every statement in a program is executed at least once.

Statement Coverage



⌘ The principal idea:

☐ unless a statement is executed,

☐ we have no way of knowing if an error exists in that statement.

Statement coverage criterion



⌘ Based on the observation:

☐ an error in a program can not be discovered:

☒ unless the part of the program containing the error is executed.

Statement coverage criterion



⌘ Observing that a statement behaves properly for one input value:

☐ no guarantee that it will behave correctly for all input values.

Example



```
⌘ int f1(int x, int y){  
⌘ 1  while (x != y){  
⌘ 2    if (x>y) then Euclid's GCD Algorithm  
⌘ 3        x=x-y;  
⌘ 4    else y=y-x;  
⌘ 5 }  
⌘ 6 return x;      }
```

Euclid's GCD computation algorithm

⌘ By choosing the test set
 $\{(x=3, y=3), (x=4, y=3),$
 $(x=3, y=4)\}$

☑ all statements are executed at least once.

Branch Coverage



⌘ Test cases are designed such that:

- ☑ different branch conditions

- ☒ given true and false values in turn.

Branch Coverage



⌘ Branch testing guarantees statement coverage:

☑ a stronger testing compared to the statement coverage-based testing.

Stronger testing

⌘ Test cases are a superset of a weaker testing:

☑ discovers at least as many errors as a weaker testing

☑ contains at least as many significant test cases as a weaker test.

Example



```
⌘ int f1(int x,int y){  
⌘ 1 while (x != y){  
⌘ 2     if (x>y) then  
⌘ 3         x=x-y;  
⌘ 4     else y=y-x;  
⌘ 5 }  
⌘ 6 return x;      }
```

Example



⌘ Test cases for branch coverage can be:

⌘ $\{(x=3, y=3), (x=3, y=2), (x=4, y=3), (x=3, y=4)\}$

Condition Coverage

⌘ Test cases are designed such that:

- ▢ each component of a composite conditional expression

- ▢ given both true and false values.

Example



⌘ Consider the conditional expression

⌘ $((c1.\text{and}.c2).\text{or}.c3):$

⌘ Each of $c1$, $c2$, and $c3$ are exercised at least once,

⌘ i.e. given true and false values.

Branch testing

⌘ Branch testing is the simplest condition testing strategy:

⏏ compound conditions appearing in different branch statements

⊗ are given true and false values.

Branch testing



⌘ Condition testing

☑ stronger testing than branch testing:

⌘ Branch testing

☑ stronger than statement coverage testing.

Condition coverage

⌘ Consider a boolean expression having n components:

☑ for condition coverage we require 2^n test cases.

Condition coverage



⌘ Condition coverage-based testing technique:

☑ practical only if n (the number of component conditions) is small.

Path Coverage



⌘ Design test cases such that:

☑ all linearly independent paths in the program are executed at least once.

Linearly independent paths

⌘ Defined in terms of
▣ control flow graph (CFG) of
a program.

Path coverage-based testing

⌘ To understand the path coverage-based testing:

☐ we need to learn how to draw control flow graph of a program.

Control flow graph (CFG)

⌘ A control flow graph (CFG) describes:

▢ the sequence in which different instructions of a program get executed.

▢ the way control flows through the program.

How to draw Control flow graph?

⌘ Number all the statements of a program.

⌘ Numbered statements:

☐ represent nodes of the control flow graph.

How to draw Control flow graph?

⌘ An edge from one node to another node exists:

☒ if execution of the statement representing the first node

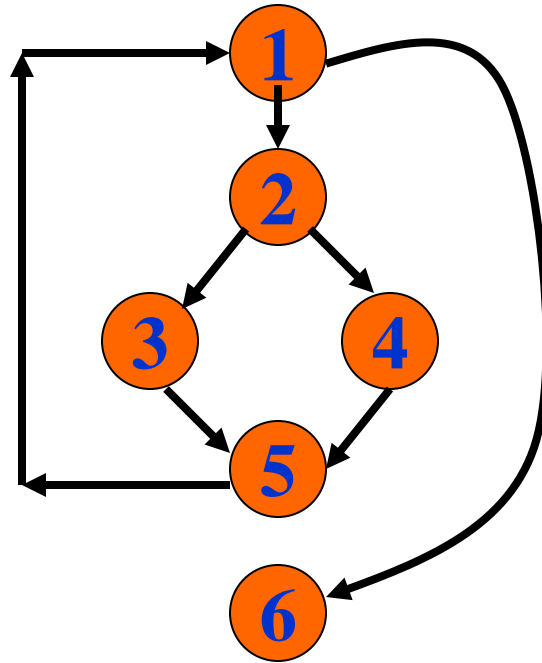
☒ can result in transfer of control to the other node.

Example



```
⌘ int f1(int x,int y){  
⌘1  while (x != y){  
⌘2    if (x>y) then  
⌘3        x=x-y;  
⌘4    else y=y-x;  
⌘5 }  
⌘6 return x;    }
```

Example Control Flow Graph

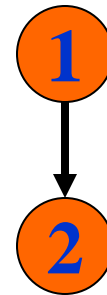


How to draw Control flow graph?

⌘ Sequence:

▣1 $a=5;$

▣2 $b=a*b-1;$



How to draw Control flow graph?

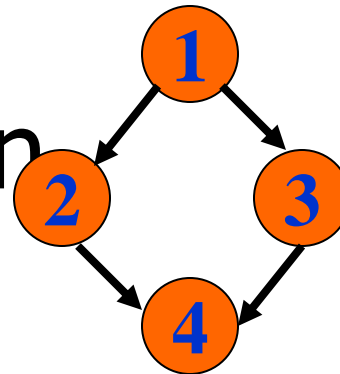
⌘ Selection:

☐ 1 if($a > b$) then

☐ 2 $c = 3;$

☐ 3 else $c = 5;$

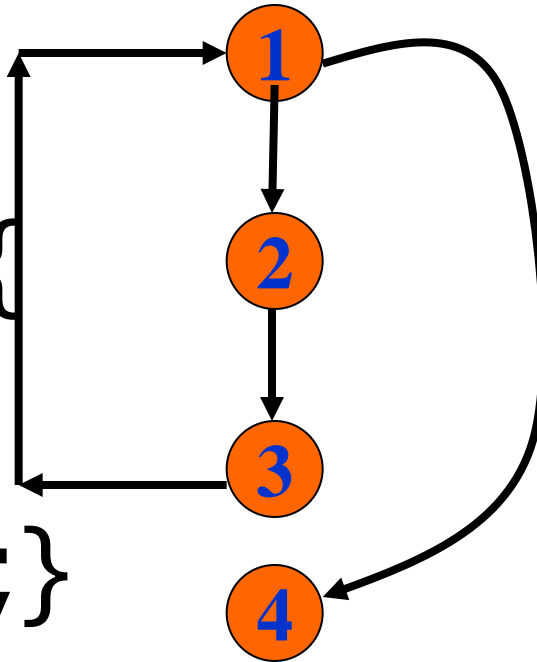
☐ 4 $c = c * c;$



How to draw Control flow graph?

⌘ Iteration:

```
⌘ 1 while(a>b){  
⌘ 2     b=b*a;  
⌘ 3     b=b-1;}  
⌘ 4 c=b+d;
```



Path



⌘ A path through a program:

☐ a node and edge sequence from the starting node to a terminal node of the control flow graph.

☐ There may be several terminal nodes for program.

Independent path

⌘ Any path through the program:

☐ introducing at least one new node:

☒ that is not included in any other independent paths.

Independent path



⌘ It is straight forward:

☑ to identify linearly independent paths of simple programs.

⌘ For complicated programs:

☑ it is not so easy to determine the number of independent paths.

McCabe's cyclomatic metric



- ⌘ An upper bound:

- ⏏ for the number of linearly independent paths of a program

- ⌘ Provides a practical way of determining:

- ⏏ the maximum number of linearly independent paths in a program.

McCabe's cyclomatic metric

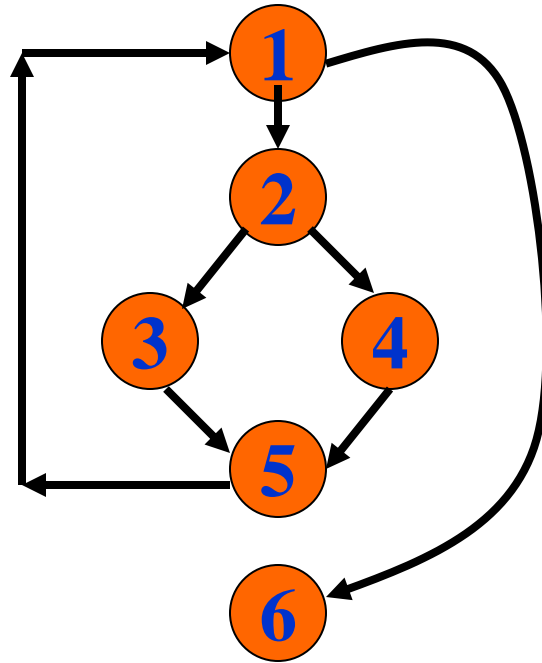
⌘ Given a control flow graph G ,
cyclomatic complexity $V(G)$:

⌘ $V(G) = E - N + 2$

⌘ N is the number of nodes in G

⌘ E is the number of edges in G

Example Control Flow Graph



Example



⌘ Cyclomatic complexity =
 $7 - 6 + 2 = 3.$

Cyclomatic complexity

⌘ Another way of computing cyclomatic complexity:

- ☐ inspect control flow graph

- ☐ determine number of bounded areas in the graph

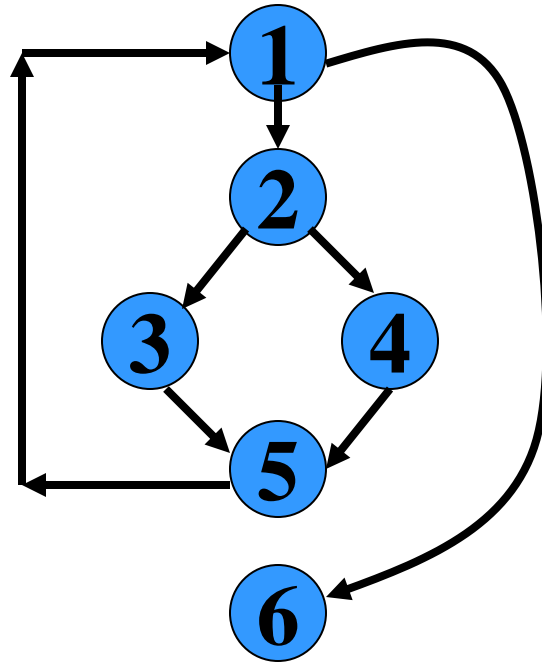
⌘ $V(G) = \text{Total number of bounded areas} + 1$

Bounded area



⌘ Any region enclosed by a nodes and edge sequence.

Example Control Flow Graph



Example



⌘ From a visual examination of the CFG:

☐ the number of bounded areas is 2.

☐ cyclomatic complexity = $2+1=3$.

Cyclomatic complexity

⌘ McCabe's metric provides:

☒ a quantitative measure of testing difficulty and the ultimate reliability

⌘ Intuitively,

☒ number of bounded areas increases with the number of decision nodes and loops.

Cyclomatic complexity

- ⌘ The first method of computing $V(G)$ is amenable to automation:
 - ☑ you can write a program which determines the number of nodes and edges of a graph
 - ☑ applies the formula to find $V(G)$.

Cyclomatic complexity

⌘ The cyclomatic complexity of a program provides:

- ☑ a lower bound on the number of test cases to be designed
- ☑ to guarantee coverage of all linearly independent paths.

Cyclomatic complexity

- ⌘ Defines the number of independent paths in a program.
- ⌘ Provides a lower bound:
 - ⏏ for the number of test cases for path coverage.

Cyclomatic complexity

- ⌘ Knowing the number of test cases required:
 - ☒ does not make it any easier to derive the test cases,
 - ☒ only gives an indication of the minimum number of test cases required.

Path testing



⌘ The tester proposes:

☑ an initial set of test data using his experience and judgement.

Path testing



⌘ A dynamic program analyzer is used:

- ☑ to indicate which parts of the program have been tested

- ☑ the output of the dynamic analysis

- ☒ used to guide the tester in selecting additional test cases.

Derivation of Test Cases



⌘ Let us discuss the steps:

☑ to derive path coverage-based test cases of a program.

Derivation of Test Cases

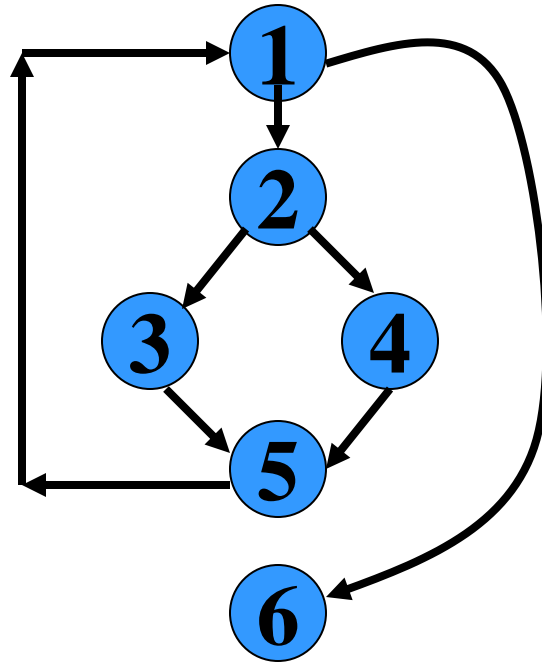
- ⌘ Draw control flow graph.
- ⌘ Determine $V(G)$.
- ⌘ Determine the set of linearly independent paths.
- ⌘ Prepare test cases:
 - ☑ to force execution along each path.

Example



```
⌘ int f1(int x,int y){  
⌘1  while (x != y){  
⌘2    if (x>y) then  
⌘3        x=x-y;  
⌘4    else y=y-x;  
⌘5 }  
⌘6 return x;      }
```

Example Control Flow Diagram



Derivation of Test Cases

⌘ Number of independent paths: 3

☒ 1,6 test case (x=1, y=1)

☒ 1,2,3,5,1,6 test case(x=1, y=2)

☒ 1,2,4,5,1,6 test case(x=2, y=1)

An interesting application of cyclomatic complexity

⌘ Relationship exists between:

- ☐ McCabe's metric

- ☐ the number of errors existing in the code,

- ☐ the time required to find and correct the errors.

Cyclomatic complexity

⌘ Cyclomatic complexity of a program:

☒ also indicates the psychological complexity of a program.

☒ difficulty level of understanding the program.

Cyclomatic complexity

- ⌘ From maintenance perspective,
 - ☒ limit cyclomatic complexity
 - ☒ of modules to some reasonable value.
 - ☒ Good software development organizations:
 - ☒ restrict cyclomatic complexity of functions to a maximum of ten or so.

Summary



⌘ White box testing:

- ☑ requires knowledge about internals of the software.

- ☑ Design and code is required.

Summary



⌘ We have discussed a few white-box test strategies.

- ☑ Statement coverage

- ☑ branch coverage

- ☑ condition coverage

- ☑ path coverage

Summary



⌘ A stronger testing strategy:

- ☑ provides more number of significant test cases than a weaker one.

- ☑ Condition coverage is strongest among strategies we discussed.

Summary



- ⌘ We discussed McCabe's Cyclomatic complexity metric:
 - ☒ provides an upper bound for linearly independent paths
 - ☒ correlates with understanding, testing, and debugging difficulty of a program.